



Morphological and Mechanical Characteristics of Onion Seedlings Insight to Mechanized Transplantation

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ABSTRACT

Background: Onion is a widely accepted as vegetable as well as spice crop, sharing a 14.31 lakh ha area with 267.3 lakh MT production in 2020. Improved management structure and healthy seedling are important factors in overcoming the cause and even developing effective transplanter. The information of morphological properties is essential before designing modern farming equipment.

Methods: Present study focuses on the properties and age of seedlings for automated transplanting, five majorly cultivated varieties of onion Light red gavrán, N-53 Nasik red, AFDR, KSP-117 and Nafed were selected. The morphological (height, weight, diameter) and mechanical (compressive strength and static coefficient of friction) properties were measured under 10 days intervals to compare 30-70 days seedling.

Result: Bulb and stem diameter were in the range from 2.82 to 3.82 mm and 0.86 to 2.12 mm, respectively. The model was found significantly different with concerning days. Plywood and aluminium had less influence on the seedling's outer surface moisture content. The morphological parameters and compressive strength increased while a static coefficient of friction reduced with an increase in the age of the seedling. Regression and ANN (using FFBP method) models were developed for the prediction of compressive strength of seedling stem as well as a bulb with respect to the age and diameter. The ANN model was found best with the coefficient of determination of 0.76. It is concluded that 60 and 70 days, seedling is best suited for mechanical or automated transplanting.

Key words: ANN models, Diameter, Morphological properties, Mechanical properties, Onion seedling, Regression.

INTRODUCTION

Onion is a bulb-oriented spice crop, except root all other parts viz. bulb, stem and leaves are edible. The onion growing area in the country was 14.31 lakh ha in 2020, with production of 267.3 lakh metric ton (MT). For transplanting operation of onion cultivation, manual transplanting is majorly adopted traditionally. This method is expensive and labour consuming due to close spacing than other vegetable crop, which can be significantly reduced by mechanization. Healthy seedling transplanted mechanically on the field also provide the best opportunity to harvest the onion in a mechanized way with providing uniform growth in whole field.

The information of morphological properties is essential before designing modern farming equipment. Properties of seedlings such as height, diameter, canopy of seedlings is required parameters for design and safety of the transplanting machine (Khadatkar *et al.*, 2020). Careful handling of seedlings with minimum damage, depends on the components' working pattern during transplanting operation. Automation is based upon seedlings' characteristics in relation to crop ecology and physiology (Sakaue, 1996). A proper age of the seedlings is important to provides the adequate strength required for mechanical transplanting, which will reduce damage, increase the survival rate and viability. But very few literatures (Pandirwar *et al.*, 2015; Khadatkar *et al.*, 2020) are available in the area of morphological properties of onion seedlings in relation to transplanting mechanism.

Plug, pot and bare root seedlings are mostly preferred under different mechanical way of transplanting. Handheld,

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semi-automatic, automatic and robotic transplanting mechanisms have been developed by using the versatile properties of seedlings. Handheld vegetable transplanter developed by Nandede *et al.* (2017) are considered mainly compressive strength property to resist the damage during gravity drop from certain height and correctly transplanted. Semi-automatic transplanter was developed by many researchers with using various mechanism for, plug and pot type seedlings [Chaudhari *et al.*, 2002 (finger type); Pandirwar *et al.*, 2019 (plug and finger type) and; Nandede, 2013 (multi stalk of metering wheel with slotted plate)]. Bare root seedlings are transplanted by plug and finger type mechanism, it works based on compressive strength of seedling stem. Height and stem diameter also influences the design of mechanism. In a gravity drop system, weight of bare root seedling influences majorly the transplanting performance. Therefore, effective age of seedling needed to acquire higher weight.

Some researchers have developed the automatic transplanting mechanism, using the different properties of seedling, [Vivek *et al.*, 2017 (automatic pneumatic gripping type mechanism); Kumawat *et al.*, 2020 (conveying belt with cutting unit for hexagonal shape paper pot chain); Khadatkar *et al.*, 2020 (embedded system)]. Pneumatic gripping type system needed adequate strength of seedling to protect from damage during gripping and releasing. For robotic transplanting, robotic arm and its gripping system were developed based on corresponding height and other factors. A Robotic transplanting mechanism was also developed by K. Rahul (2020) 4 DOF parallel robotic arm. The picking and placing are carried out with using a gripper arm. This also requires the base properties of seedling as input. Hence, the basic information about the seedling is needed to design and development of transplanter.

This study focused to evaluate the morphological and mechanical properties of different varieties of onion seedlings, which could be useful to provide the paramount information for design and development of onion seedlings transplantation in a mechanical way.

MATERIALS AND METHODS

Research was conducted on June 2020 with five different varieties of onion at Central Institute of Agricultural Engineering, Bhopal. The onion varieties namely, Light red *gavran*, N-53 *Nasik red*, AFDR, KSP-117 and Nafed were selected. These varieties are widely cultivated in the central region of India. Seeds of onion were planted in well pulverized clay soil (Vertisols). Standard agronomical procedures were followed to prepare the nursery. Seedlings were matured after 35-40 days (Anonymous 2021) to transplant into the field but higher strengthened seedling is needed in the aspect of mechanical transplanting for which this span is increased. Morphological parameters were observed during the period from the age of 30 days to 70 days. Onion seedling's sample were randomly collected from the field and fifty samples were collected from each plot to take the different parameters.

Moisture content

It is necessary to have proper knowledge about exact moisture content of seedlings to know the interaction effect with mechanical equipment's. ASAE Standard (1997) S358.2 (DEC93) was used for finding the moisture content (wet basis). The seedling samples were cut into thin pieces and kept into the oven at 103°C for the period of 24 hours. Moisture content of seedling was determined by observing the weight for fresh and oven dry seedlings by the weighing balance having least count 0.0001 g (Make by Citizen CY 304).

Weight of seedling (with and without de-topping)

Slightly heavier seedling with adequate strength is a necessity for mechanical/automatic transplanting, especially for bare root seedlings. Hence, the weight of onion seedlings with and without de-topping was measured. Ten observations

were taken with three replications by using weighing balance 'Citizen CY 304' having least count 0.0001 g.

Linear dimension of seedlings

The maximum length of outer edge of onion bulb were measured bulb diameter while the stem diameter measured at the collar (upper portion of onion bulb) by using vernier calliper having least count 0.01 mm (make: Baker; model: SDN 30). For this study, twenty-five observations were taken and data was analysed.

Height of seedling is important factor from designing point of view and to determine the length of plugs and fingers, dropping funnel length and alignment, press wheel diameter. However, de-topping is needed before mechanical transplant (Pandirwar *et al.*, 2015) due to the unwanted interference by longer seedlings (30-40 cm) with maintaining the intra row spacing *i.e.*, recommended about 10 cm. Five times observations were taken for each variety and measured by the meter tape.

Coefficient of static friction

Appropriate material enhances the effectiveness of transplanting machines' performance and assisted to the reduction of total casting of machine. Hence, coefficient of friction was measured for five materials *viz* Plywood (W), Plastic (P), Mild steel (MS), Aluminium (Al) and Stainless steel (SS) for full and de-topped seedlings. The seedlings were put along the slope into the horizontal platforms. It was gently inclined the platform up until the seedling slipped (Impending slip) at a certain angle. It was recorded and computed by following equation:

$$\mu = \tan \delta \quad \dots(1)$$

Where,

μ = Coefficient of friction.

δ = Impending slip angle, degree.

Compressive strength

The ability of a seedling to resist mechanical interference indicates its strength. The compressive strength of onion bulb and stem were measured through the texture analyser (TA.XT.Plus; make:Stable Micro System,UK) having load capacity 50 kg, by using the half inch cylindrical ebonite probe having 25 mm diameter were used. It was compressed about 30% of bulb and stem diameter, with 0.5 mm/s test speed to find the strength as well as to minimize the seedling damage and mortality (Pandirwar *et al.* 2015).

Comparison to the approach for prediction of compressive strength

Robotic transplanting or automation mainly works based on its model, which works behind the layer, by using many components *i.e.*, languages, micro-controller, manipulator, actuator *etc.* Many types of mathematical and statistical models were used to solve complex problem for doing any specific task by using basic physical properties of the agricultural products. The prediction of compressive force of seedling is needed for actuating the gripping arm within

safest limit of seedling. Under this study, two methods were used to develop the model for predicting compressive strength and comparison. Specified 125 observations were selected for onion bulb and 50 observations were taken for stem of seedlings. Empirical model (multiple linear regression) was developed for predicting the compressive strength of onion seedling stems and bulbs. On other hand, neural network approach was used to predict the compressive force. Both methods were compared on the basis of its findings.

Regression approach

Multiple linear regression was used to develop model to predict compressive strength of onion seedling stem and bulb. Model was generated by using Weka 3.9.5. The independent parameters were considered as day and diameter of bulb/stem. Correlation and multiple linear regression were observed at 5% level of significance. The equation is stated as

$$Y = a X_1 + b X_2 + C \quad \dots(2)$$

Where,

Y = Compressive strength, N.

X_1 = Number of days.

X_2 = Diameter of seedling bulb/stem, mm.

a, b, C = constant.

Neural network approach

An artificial neural network functions by combining a number of nodes called artificial neurons. In neurons, a signal is sent only if it crosses a certain threshold. A pair of interconnected artificial neurons could transmit and coordinate information under different layers via signal. ANN directly learns and makes a relationship between input (X) and output (Y). Between the input and output layers, a number of hidden layers are available, so that a feed-forward backpropagation network is generated in this manner (Nagar, 2020). The basic structure was shown in Fig 1.

Neural network was applied for the prediction model with collected data of onion bulb and stem and was evaluated using MATLAB R2016a. An equal number of observations were taken, as in regression approach. Some parameters

were fed for creating the feed forward back propagation network, such as number of input layer = 1; output layer = 1; hidden layer = 1; number of neurons = 2; Levenberg-Marquardt transfer function (trainlm) are used for training (Dahikar *et al.*, 2015). Training, validation and testing were done during prediction model process and evaluate both models.

Statistical analysis of morphological properties of onion seedling

Morphological parameters of onion seedlings were collected for different days at specific intervals and analysed in SAS 9.3 for finding the ANOVA under factorial experiment in CRD (Completely randomised design). The analysis was done and observed at 1% level of significance.

RESULTS AND DISCUSSION

The experiments were conducted to evaluate the morphology of onion seedlings *i.e.*, linear and frictional properties as discussed. The appropriate age of seedlings can be decided in the aspect of mechanical transplanting. Data were collected by using seedlings' age from 30 to 70 days after sowing.

Seedling moisture content

The average moisture content (wet basis) of onion seedlings for all five varieties was found in the range which varied from 88.91% to 92.83% under all day's observations. Its standard deviation varied from 0.62 to 4.56%. Moisture content was recorded between 91.84 to 90.68 % (Light red *gavran*); 92.83 to 90.65% (N-53 *Nasik red*), 92.64 to 91.62% (AFDR), 91.33 to 91.76% (KSP-117) and 91.57 to 89.27% (Nafed), respectively for 30 to 70 days. The moisture content of seedling was slightly reduced with age in all the varieties and this result was in agreement with Pandirwar *et al.*, (2015).

Weight of seedlings

The weight of bare root onion seedling was measured as depicted in Table 1. It was further measured de-topped and dry weight of seedling. The growth rate was found higher in Light red *gavran* variety while the lowest growth was found in KSP-117. The higher weight of seedling was found for

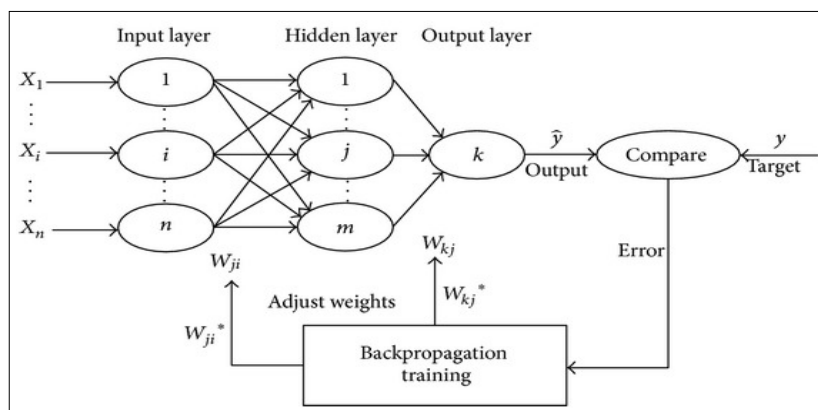


Fig 1: Feed forward and back propagation neural network structure.

Table 1: Weight of onion seedling of different varieties at different growing stage.

Days	30	40	50	60	70
Light Red Gavran					
W_{sw} , mg	234±49.2	324±74.2	623.02±251.6	901.38±116.3	964.54±206.6
W_{dtpw} , mg	170±31.0	222±11.7	556.38±159.4	436.1±177.9	650.34±83.5
W_{sdrw} , mg	17.84±4.0	33.03±9.9	59.74±24.8	66.94±21.4	80.34±14.3
N-53 Nasik Red					
W_{sw} , mg	212±70.5	284±53.9	444.54±106.2	703.64±114.5	751.84±153.8
W_{dtpw} , mg	146±41.8	230±49.8	268.28±52.8	494.94±87.1	505.2±76.9
W_{sdrw} , mg	16.72± 5.6	27.17±7.2	42.84±7.8	53.16±10.3	57.56±10.8
AFDR					
W_{sw} , mg	263.72±65.3	325.54±97	405.6±164.9	378.44±99.9	786.92±168.5
W_{dtpw} , mg	201.06±47.6	369.26±121.2	280.64±67.6	532.5±85	459.32±27.2
W_{sdrw} , mg	19.88±3.6	31.54±10.1	49.58±12.5	42.04±8.6	77.38±3.5
KSP-117					
W_{sw} , mg	254.26±78.4	287.12±146.9	223.56±113.3	491.26±124.9	412.7 ±134.8
W_{dtpw} , mg	212.14±53.1	246.86±74.9	264.92±90	370.3±99.3	420.04±95.9
W_{sdrw} , mg	23.02±7.6	24.84±13.3	24.12±12.2	51.14±16.8	50.08±12.7
Nafed					
W_{sw} , mg	405.9±172.9	448.2±30.5	640.12±236.3	679.54±138.5	519.24±219.7
W_{dtpw} , mg	256.16±111.5	311.42±7.2	438.5±181.2	489.22±56.5	519.64±180.2
W_{sdrw} , mg	31.66 ±2.1	39.34±17.0	47.36±15.6	58.92±11.6	58.54±10.6

W_{sw} - Seedling weigh; W_{dtpw} - De-topped seedling weight; W_{sdrw} - Seedling dry weight.

Light red *gavran* and it was 964.54 mg, 65.34 mg and 80.34 mg for full, de-topped and dry weight seedling, respectively, among all varieties.

Similarly, the lowest weight was found as 412.7, 420.04 and 50.8 mg for full, de-topped and dry seedlings in KSP-117. The statistical model was found difference significantly (at 1% level of significance) in aspect of days for seedling weight, de-topped weight and dry weight as well. Similarly, the significant difference found among all varieties for seedling dry weight. The major reason in the variation of the weight was the quality of different varieties. It may be due to change in environmental conditions during seedlings' growth.

Number of leaves

There was no significant difference observed in number of leaves among all varieties; However, it was significantly different with respect to days. The number of leaves per plant were observed to be in the range from 2 to 4 during nursery stage. The maximum growth rate of leaves was observed for Light red *gavran* and N-53 *Nasik red* variety. It was found to be 3.4±0.49 and 3.2±0.40 for Light red *gavran* and N-53 *Nasik red* variety, respectively.

Bulb and stem diameter of seedling

The onion bulb and stem diameter are depicted in Table 2, which reflect the growing status of factors in the nursery stage. The onion bulb diameter was found in the range from 1.28 to 3.82 mm from 30 to 70 days after planting. Maximum bulb diameter was observed as 3.82 ± 0.66 mm under AFDR variety, while lowest diameter was found as 2.82 ± 0.58 mm for N-53 *Nasik red* during the same period. On other hand,

the maximum stem diameter was observed as 2.12 ± 0.58 mm for Nafed, followed by AFDR, N-53 *Nasik red*, Light red *gavran* and KSP-117.

Height of seedling

The seedling height is presented for all five varieties in Table 2, from 30 to 70 days growth period, was observed from 115 to 263 mm and reflected gradual increment during nursery growing. However, after 60 days of planting, these increments reduced slightly due to adverse climate conditions. Among all five varieties the maximum height (263 mm) was found in Nafed, followed by N-53 *Nasik red* (234 mm), Light red *gavran* (232 mm), AFDR (192 mm) and KSP-117 (158 mm), respectively. The height of seedlings was reduced by de-topping process prior to transplanting operation thereby seedling uniformity acquired for effective mechanical handling.

The comparative evaluation shows that onion seedling weight increased gradually with increasing the physical parameters (height and diameter of seedling) (Fig 2a). Seedling weight increased from 282.43 to 631.67 mg with increasing the bulb diameter from 1.96 to 3.24 mm during 30 to 70 days observation (Fig 2b). The value was slightly lower than that observed by Pandirwar *et al.*, (2015) and Khadatkhar *et al.*, (2020) and the reason behind this may be the nursery grown under shadenet. Linear relation was observed between stem and bulb diameter of seedling. The coefficient of determination was found as 0.96 (Fig 2c), which depicts the higher relation between them. The analysis would be assisted to future automation in transplanting system.

Table 2: No. of leaves, height, bulb and stem diameter of onion seedlings.

Days	30	40	50	60	70
Light Red Gavraan					
No.	2.2±0.4	2.2±0.40	3	3±0.63	3.4±0.49
H, mm	160±28.3	161±23.1	193±30.3	230±20.0	232±29.1
D _B , mm	1.82±0.33	1.72±0.15	2.92±0.87	3.28±0.31	3.65±0.66
D _S , mm	1.16±0.20	1.08±0.20	1.86±0.30	1.72±0.20	1.88±0.50
N-53 Nasik Red					
No.	2	2.2±0.40	3	2.6±0.49	3±0.63
H, mm	125±28.6	179±21.1	198±21.4	214±32.6	234±56.8
D _B , mm	1.28 ±0.21	1.66±0.14	2.93±0.50	2.18±0.36	2.82±0.58
D _S , mm	0.86±0.10	1.12±0.10	1.72±0.20	1.58±0.30	1.92±0.30
AFDR					
No.	3	2.6±0.49	2.2±0.75	2.8 ± 0.40	2.4±0.49
H, mm	115.4 ±10.6	187±30.9	177.2±25.4	180 ± 31.6	192±18.6
D _B , mm	1.86 ±0.47	2.7±0.28	2.76±0.54	3.38 ± 0.99	3.82±0.66
D _S , mm	0.86 ±0.20	1.38±0.10	1.63±0.30	2.08 ± 0.30	2.02±0.60
KSP-117					
No.	2.2±0.40	2.6±0.50	1.6±0.50	2.4 ± 0.50	3
H, mm	130±7.1	168±18.6	120±30.3	209 ± 19.6	158±14.4
D _B , mm	2.62± 0.77	2.69±0.57	3.14±1.23	3.2 ± 0.52	3.48±0.96
D _S , mm	0.88± 0.10	1.32±0.40	1.48±0.20	1.78 ± 0.20	1.82±0.40
Nafed					
No.	2.2±0.40	2.6±0.49	2.4±0.49	3±0.63	3.2±0.40
H, mm	12 ±17.2	163±34.3	201±19.6	207±30.6	263±29.7
D _B , mm	2.22±0.19	2.56±0.39	2.58±0.74	3.3±0.72	3.52±0.35
D _S , mm	0.96±0.19	1.59±0.46	1.61±0.42	2.1±0.33	2.12±0.58

No- Number of leaves; H- Height of seedlings; D_B- Bulb diameter; D_S- Stem diameter of seedlings.

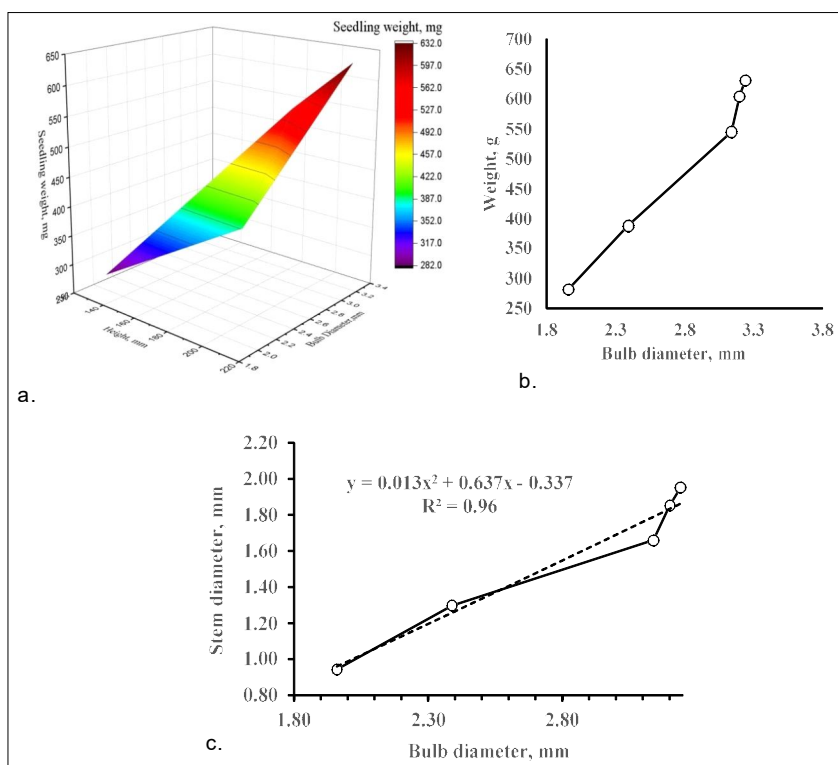


Fig 2: Relation of different parameters of onion seedlings; a. Seedling weight, bulb diameter and height; b. weight and bulb diameter; c. stem diameter and bulb diameter.

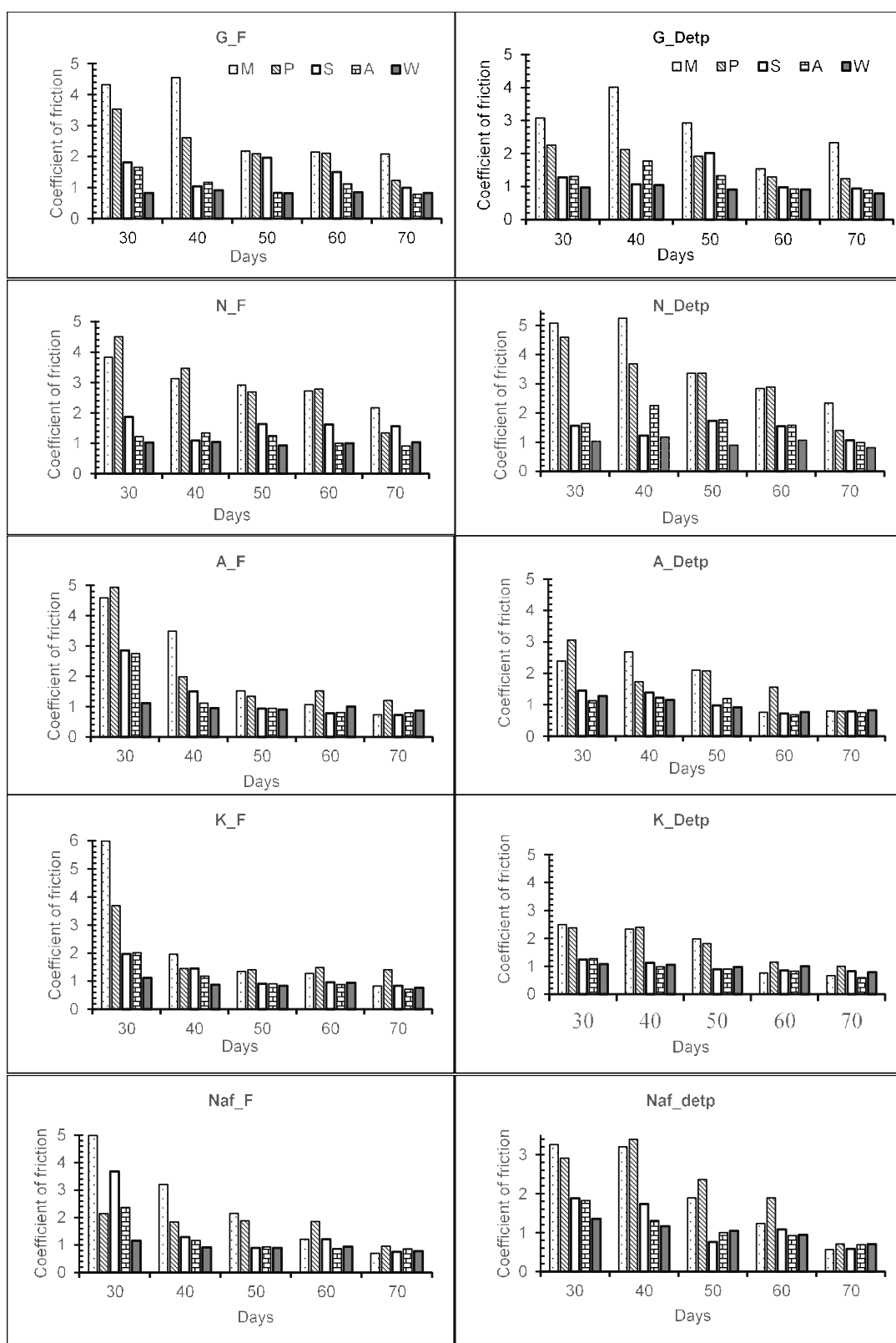


Fig 3: Coefficient of friction under different varieties for full (F) and detopped (detp) seedling, G- Gavran; N- Nasik Red; A- AFDR; K- KSP-117 and Naf- Nafed.

Coefficient of static friction (CF)

The average coefficient of friction (Fig 3) was found in the range between 0.70 to 1.35, 0.71-4.94, 0.66-5.24, 0.69-2.26 and 0.58-3.68 for Plywood (W), Plastic (P), Mild steel (MS), Aluminium (Al) and Stainless steel (SS), respectively. Plastic shows the higher CF among all platforms, but the nature of gradual reduction of CF with age of seedling are similar as findings by other researchers. The significant differences were found in CF with respect to the varieties, age of seedlings as well as with used platforms (at 1% level of significance). The CF had reciprocal relation with age of seedlings.

Thirty days old onion seedling (not matured properly) had higher coefficient of friction due to more soft, flexible and lighter in weight. Another reason of higher CF are the shorter leaves of seedlings, which adhere easily to the material surface and do not allow seedling to displace from specified position. Seedling weight increased with age. Thereby higher weight, easily assisted to displace the seedling during operation and did not affect much by the outer surface moisture content of seedling. Thus, they roll down at a lower static friction (Khura *et al.*, 2010; Pandirwar *et al.*, 2015). Based on findings plastic material had higher CF as compared to other materials (Fig 3). Plywood and Aluminium material had affected less by the moisture content of seedling. Its variation was found less with increment in

age. On other hand, higher age seedling (60 to 70 day) had lesser coefficient of friction, as compared to lower age seedling.

Compressive strength

The compressive strength of bulb/stem of seedling is presented in Fig 4. The mean value of bulb and stem of onion seedling ranged from 5.44 to 12.74 N and 2.46 to 7.23 N, respectively. The maximum value of CS of bulb was 13.21 N at 70 days for Nafed variety while minimum was observed as 4.77 N at 30 days for AFDR variety Seedling's bulb exhibits significant differences for varieties and days, whereas the stem only showed a significant difference for days. The maximum CS was 8.13 N at 70 days of stem for KSP-117 and minimum CS was 1.87 N at 30 days for Light red *gavran* variety.

As bulb and stem diameters increased, CS gradually increased. Findings are supported with the conclusion by Khura *et al.* (2010). A 60 to 70-day-old onion seedling was found to be more appropriate and easier to transplant using an automatic or mechanical transplanter that is more robust. Observed data of physical parameters of seedlings may helpful for designing of transplanter to smooth operation of transplanter and for automation. Seedling bulb diameter and stem diameter had a strong relation to transplanter. The coefficient of determination was found to be 0.98 and 0.97 for bulb and stem of onion seedling, respectively.

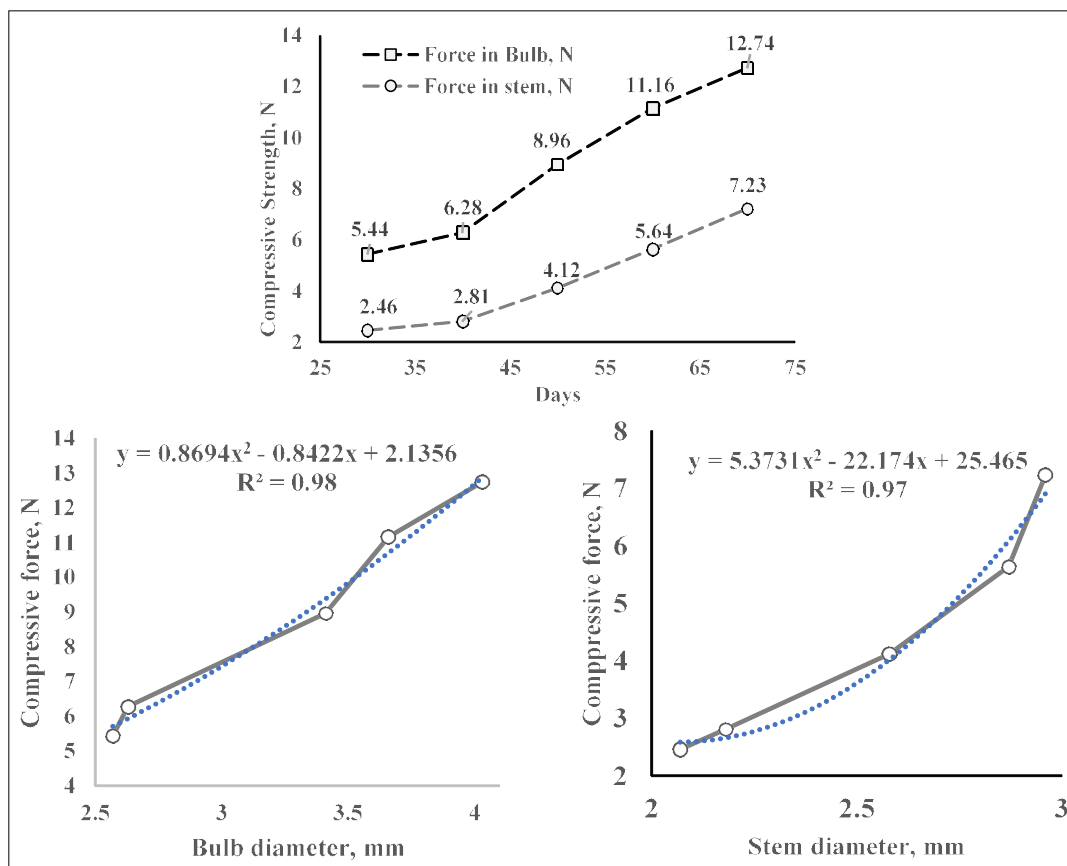


Fig 4: Compressive strength of bulb and stem of onion seedling with respect to days, bulb diameter and stem diameter.

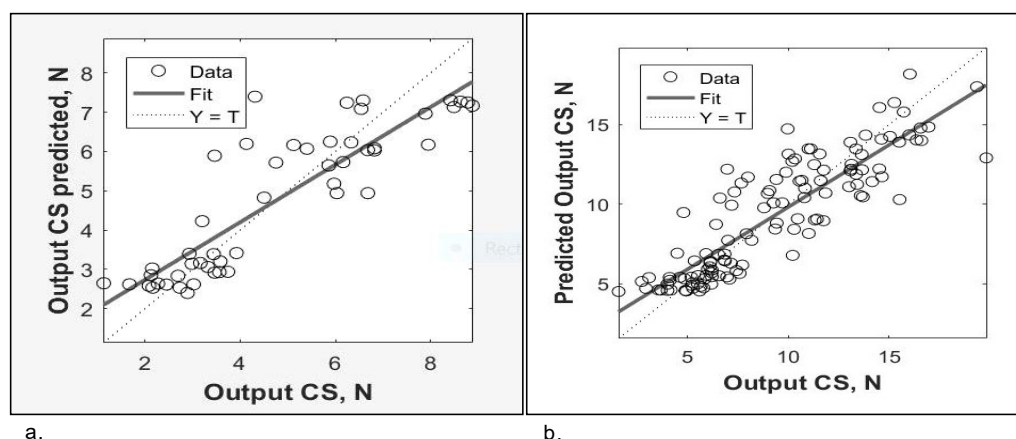


Fig 5: Compressive strength of stem (a) and bulb (b) with its predicted value.

Regression analysis

The multiple regression analysis was done to predict the compressive strength of onion seedlings' stem and bulb. The imperial equation (Table 3) was developed to predict the strength by taking two independent variables as number of days and diameter of seedlings. The multiple regression with proposed equation was found to be fit with the value 0.75 for coefficient of determination (R^2) of onion bulb and stem, while its root mean square error (RMSE) was found to be 2.02 and 1.07, in same manner respectively. The overall regression model was highly significant at, $F(2, 122) = 200.84$, $p < 0.001$ and both parameters are significant with the compressive strength.

Neural network approach

On the basis of physical observations of the parameters, data were trained for generating an artificial neural network (ANN) for prediction model for onion bulbs and stem's compressive strength. 70% data was taken as training data while remaining data was divided in equal division and used for validation and testing purpose. Levenberg-Marquardt back propagation training program were taken with 500 epochs to predict the output regarding CS of stems and bulbs. According to the training, validation and testing of the data for onion stem and bulb compressive strength, prediction model follows as:

$$\text{Predicted Stem CS} = 0.6 \text{ stem CS} + 1.9 \quad \dots(3)$$

$$\text{Predicted Bulb CS} = 0.72 \text{ bulb CS} + 2.1 \quad \dots(4)$$

The predicted data (Fig 5) showed the linear relation between predicted value and actual output. The coefficient of determination of stem was observed to be 0.77 while it was observed as 0.76 for onion bulb. The R^2 of training, validation and testing data of stem was 0.74, 0.64 and 0.81 % respectively while its value was found as 0.74, 0.82 and 0.88 for bulb which is slightly higher.

Neural network depicts that, it works on the principle of weight transfer between different nodes under different layers. Result shows that its predictability was higher as compared with regression method on the basis of coefficient

Table 3: Regression Model, standard error and t value for compressive strength of onion seedlings.

Parameter	Model	B	Std. error	t value
Bulb	Constant	-5.37	0.74	- 7.19
	Day (a)	0.12	0.01	7.89
	Diameter (b)	2.55	0.23	10.98
Stem	Constant	-2.36	0.61	-3.92
	Day (a)	0.112	0.013	8.34
	Diameter (b)	0.65	0.26	2.44

of determination values acquired. Hence, neural network approach is the best substitute in future for prediction in automation.

CONCLUSION

The study reveals that 60 to 70-days old seedlings are suitable for transplanting of seedlings mechanically or by automation. The moisture content of onion seedling was 92.64-89.62% (wb). during growing time period (30-70 days). The CF for different platform was varied from 5.24-0.58 during 30 to 70 days. Plywood and Aluminium had less influence to the outer moisture content of seedlings. However, CF was also found less for other material at the age of 60 to 70 days. The compressive strength increased with age of seedling. Analysis shows the ANN provided a better prediction model with a high coefficient of determination. Compressive strength used to design the optimized gripping force in automation/robotic transplanting system. Gathered information would be helpful for designing of effective transplanting mechanism of transplanter and proven technologies in an optimized way.

Conflicts of interest: None.

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